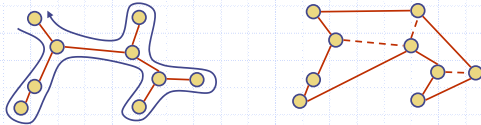


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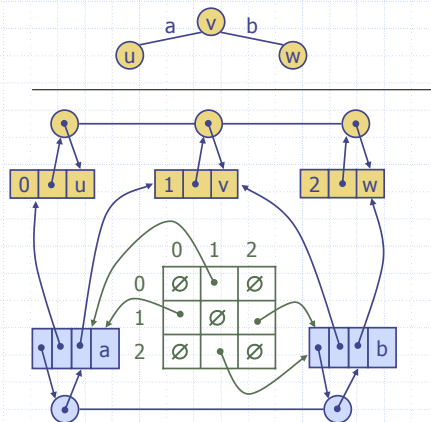


# Graph Assignment

- ◆ Goals
  - Learn and implement the adjacency matrix structure and Kruskal's minimum spanning tree algorithm
  - Understand and use the decorator pattern and various JDSL classes and interfaces
- ◆ Your task
  - Implement the adjacency matrix structure for representing a graph
  - Implement Kruskal's MST algorithm
- ◆ Frontend
  - Computation and visualization of an approximate traveling salesperson tour

# Adjacency Matrix Structure

- ◆ Edge list structure
- ◆ Augmented vertex objects
  - Integer key (index) associated with vertex
- ◆ 2D-array adjacency array
  - Reference to edge object for adjacent vertices
  - Null for non-adjacent vertices



# Kruskal's Algorithm

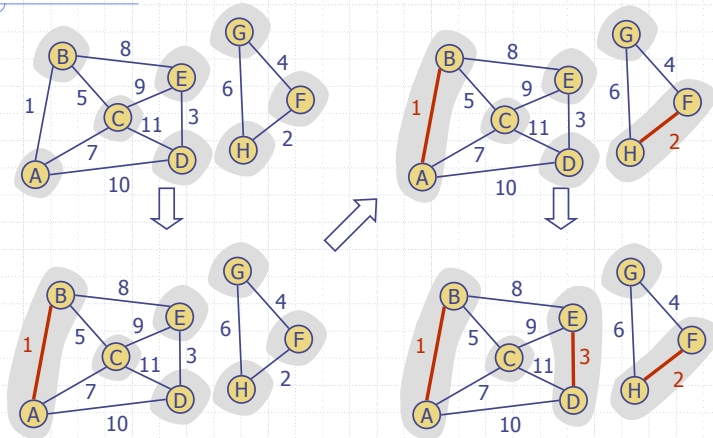
- ◆ The vertices are partitioned into clouds
  - We start with one cloud per vertex
  - Clouds are merged during the execution of the algorithm
- ◆ Partition ADT:
  - **makeSet**(*o*): create set {*o*} and return a locator for object *o*
  - **find**(*l*): return the set of the object with locator *l*
  - **union**(*A*,*B*): merge sets *A* and *B*

```

Algorithm KruskalMSF(G)
Input weighted graph G
Output labeling of the edges of a minimum spanning forest of G

Q ← new heap-based priority queue
for all v ∈ G.vertices() do
    l ← makeSet(v) { elementary cloud }
    setLocator(v,l)
for all e ∈ G.edges() do
    Q.insert(weight(e), e)
while ¬Q.isEmpty()
    e ← Q.removeMin()
    [u,v] ← G.endVertices(e)
    A ← find(getLocator(u))
    B ← find(getLocator(v))
    if A ≠ B
        setMSFedge(e)
        { merge clouds }
    union(A, B)
    
```

## Example

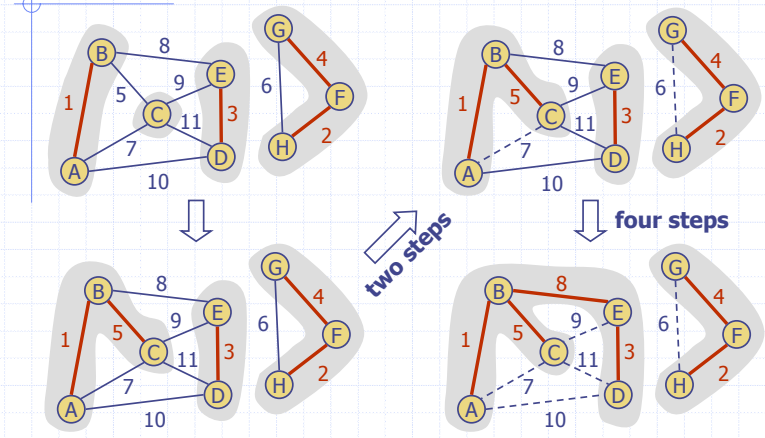


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## Example (contd.)



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## Partition Implementation

- ◆ Partition implementation
  - A set is represented the sequence of its elements
  - A position stores a reference back to the sequence itself (for operation *find*)
  - The position of an element in the sequence serves as locator for the element in the set
  - In operation *union*, we move the elements of the smaller sequence into to the larger sequence
- ◆ Worst-case running times
  - *makeSet*, *find*:  $O(1)$
  - *union*:  $O(\min(n_A, n_B))$
- ◆ Amortized analysis
  - Consider a series of  $k$  Partition ADT operations that includes  $n$  *makeSet* operations
  - Each time we move an element into a new sequence, the size of its set at least doubles
  - An element is moved at most  $\log_2 n$  times
  - Moving an element takes  $O(1)$  time
  - The total time for the series of operations is  $O(k + n \log n)$

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## Analysis of Kruskal's Algorithm

- ◆ Graph operations
  - Methods *vertices* and edges are called once
  - Method *endVertices* is called  $m$  times
- ◆ Priority queue operations
  - We perform  $m$  *insert* operations and  $m$  *removeMin* operations
- ◆ Partition operations
  - We perform  $n$  *makeSet* operations,  $2m$  *find* operations and no more than  $n - 1$  *union* operations
- ◆ Label operations
  - We set vertex labels  $n$  times and get them  $2m$  times
- ◆ Kruskal's algorithm runs in time  $O((n + m) \log n)$  time provided the graph has no parallel edges and is represented by the adjacency list structure

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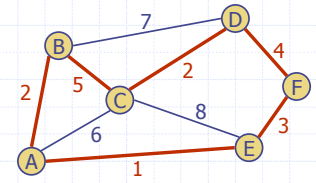
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# Decorator Pattern

- ◆ Labels are commonly used in graph algorithms
  - Auxiliary data
  - Output
- ◆ Examples
  - DFS: unexplored/visited label for vertices and unexplored/ forward/back labels for edges
  - Dijkstra and Prim-Jarnik: distance, locator, and parent labels for vertices
  - Kruskal: locator label for vertices and MSF label for edges
- ◆ The decorator pattern extends the methods of the Position ADT to support the handling of attributes (labels)
  - *has(a)*: tests whether the position has attribute *a*
  - *get(a)*: returns the value of attribute *a*
  - *set(a, x)*: sets to *x* the value of attribute *a*
  - *destroy(a)*: removes attribute *a* and its associated value (for cleanup purposes)
- ◆ The decorator pattern can be implemented by storing a dictionary of (attribute, value) items at each position

# Traveling Salesperson Problem

- ◆ A tour of a graph is a spanning cycle (e.g., a cycle that goes through all the vertices)
- ◆ A traveling salesperson tour of a weighted graph is a tour that is simple (i.e., no repeated vertices or edges) and has minimum weight
- ◆ No polynomial-time algorithms are known for computing traveling salesperson tours
- ◆ The traveling salesperson problem (TSP) is a major open problem in computer science
  - Find a polynomial-time algorithm computing a traveling salesperson tour or prove that none exists



Example of traveling salesperson tour (with weight 17)

# TSP Approximation

- ◆ We can approximate a TSP tour with a tour of at most twice the weight for the case of Euclidean graphs
  - Vertices are points in the plane
  - Every pair of vertices is connected by an edge
  - The weight of an edge is the length of the segment joining the points
- ◆ Approximation algorithm
  - Compute a minimum spanning tree
  - Form an Eulerian circuit around the MST
  - Transform the circuit into a tour

